

# Decision Theory under Imprecise Probabilities

Tutorial

Robert Hable  
Department of Mathematics  
University of Bayreuth

# Imprecise Probabilities

## Coherent Lower/Upper Previsions (Walley, 1991)

**Lower prevision:**

$$\underline{P} : \mathcal{L}_\infty(\Omega) \rightarrow \mathbb{R}, \quad f \mapsto \underline{P}[f]$$

**Upper prevision:**

$$\bar{P} : \mathcal{L}_\infty(\Omega) \rightarrow \mathbb{R}, \quad f \mapsto \bar{P}[f]$$

**Credal set**

$$\mathcal{M} = \left\{ P \text{ precise prevision} \mid \underline{P}[f] \leq P[f] \leq \bar{P}[f] \quad \forall f \in \mathcal{L}_\infty(\Omega) \right\}$$

# Decision Theory

Decision theory = Theory of “How to make good decisions, if this is necessary”

# Decision Theory

Decision theory = Theory of “How to make good decisions, if this is necessary”

- ▶ “if this is necessary” → decision problem
- ▶ “decisions” → What can be done?
- ▶ “good decisions” → Optimality criterion?

# Decision Theory

Decision theory = Theory of “How to make good decisions, if this is necessary”

- ▶ “if this is necessary” → decision problem
- ▶ “decisions” → What can be done?
- ▶ “good decisions” → Optimality criterion?

## Examples:

- ▶ Making an investment in a certain company
- ▶ Statistical decision theory:
  - ▶ Hypothesis testing: Reject the null hypothesis  $H_0$  or not?
  - ▶ Estimation of a parameter

In the following: mathematical formalization of such things

# Decisions and States of Nature

## Decisions

$\mathbb{D}$  = set of all possible decisions (actions)  $t$

## States of nature

- ▶ State of nature  $\theta$  = description of the actual situation
- ▶ Whole set of possible states of nature

$$\theta \in \Theta$$

Which  $\theta \in \Theta$  is true?  $\rightarrow$  This is unknown!

## Example: Decisions and States of Nature

### Making an Investment in a Certain Company

- ▶ States of nature  $\theta$ : success of the company
- ▶ Decisions  $t$ : whether to make an investment

	investment	no investment
Company will be very successful.	excellent	slightly bad
Company will do reasonably well.	okay	okay
Company will collapse.	disastrous	slightly good

## Example: Decisions and States of Nature

### Making an Investment in a Certain Company

- ▶ States of nature  $\theta$ : success of the company
- ▶ Decisions  $t$ : whether to make an investment

	investment	no investment
Company will be very successful.	100	-10
Company will do reasonably well.	0	0
Company will collapse.	-200	10

## Utility Function

What are the consequences of my decision  $t \in \mathbb{D}$ ?

**Utility function:**

$$u : \Theta \times \mathbb{D} \rightarrow \mathbb{R}, \quad (\theta, t) \mapsto u_{\theta}(t)$$

Every decision  $t \in \mathbb{D}$  leads to a certain utility

$$u_{\theta}(t) \in \mathbb{R}$$

depending on the (unknown) state of nature  $\theta \in \Theta$

## Utility Function

What are the consequences of my decision  $t \in \mathbb{D}$ ?

**Utility function:**

$$u : \Theta \times \mathbb{D} \rightarrow \mathbb{R}, \quad (\theta, t) \mapsto u_\theta(t)$$

Every decision  $t \in \mathbb{D}$  leads to a certain utility

$$u_\theta(t) \in \mathbb{R}$$

depending on the (unknown) state of nature  $\theta \in \Theta$

- ▶ high utility: good
- ▶ small utility: bad
- ▶ negative utility = positive loss

## Alternative: Loss Function

What are the consequences of my decision  $t \in \mathbb{D}$ ?

**Loss function instead of utility function**

$$W : \Theta \times \mathbb{D} \rightarrow \mathbb{R}, \quad (\theta, t) \mapsto W_{\theta}(t)$$

Every decision  $t \in \mathbb{D}$  leads to a certain loss

$$W_{\theta}(t) \in \mathbb{R}$$

depending on the (unknown) state of nature  $\theta \in \Theta$

## Alternative: Loss Function

What are the consequences of my decision  $t \in \mathbb{D}$ ?

**Loss function instead of utility function**

$$W : \Theta \times \mathbb{D} \rightarrow \mathbb{R}, \quad (\theta, t) \mapsto W_{\theta}(t)$$

Every decision  $t \in \mathbb{D}$  leads to a certain loss

$$W_{\theta}(t) \in \mathbb{R}$$

depending on the (unknown) state of nature  $\theta \in \Theta$

**Equivalence of loss function and utility function:**

$$W_{\theta}(t) = -u_{\theta}(t) \quad \forall t \in \mathbb{D} \quad \forall \theta \in \Theta$$

**Loss function is used in the following!**

## What is a good decision?

	investment	no investment
Company will be very successful.	excellent	slightly bad
Company will do reasonably well.	okay	okay
Company will collapse.	disastrous	slightly good

→ **Rating depends on the unknown state of nature  $\theta$ .**

## What is a good decision?

	investment	no investment
Company will be very successful.	excellent	slightly bad
Company will do reasonably well.	okay	okay
Company will collapse.	disastrous	slightly good

→ **Rating depends on the unknown state of nature  $\theta$ .**

### What can be done?

- ▶ If we have a prior distribution (prevision)  $\pi$  for  $\theta$ :
  - Deciding according to the expected loss / Bayes risk

## What is a good decision?

### Precise prior distribution

- ▶ Find a decision  $\tilde{t}$  which minimizes the “Bayes risk”

$$\pi[W.(t)] = \int_{\Theta} W_{\theta}(t) \pi(d\theta) \in \mathbb{R}$$

## What is a good decision?

### Precise prior distribution

- ▶ Find a decision  $\tilde{t}$  which minimizes the “Bayes risk”

$$\pi[W.(t)] = \int_{\Theta} W_{\theta}(t) \pi(d\theta) \in \mathbb{R}$$

### Imprecise prior distribution

- ▶ leads to a whole interval of “Bayes risks”

$$[\underline{\pi}[W.(t)], \overline{\pi}[W.(t)]] \subset \mathbb{R}$$

→ How to compare overlapping intervals?

→ Different possibilities (i.e. different optimality criteria)

## $\Gamma$ -minimax, $\Gamma$ -minimin and a mixture

### $\Gamma$ -minimax ( $\Gamma$ -maximin)

- ▶ Find a decision  $\tilde{t}_1$  which minimizes the upper bound

$$\bar{\pi}[W.(t)] = \text{upper Bayes risk}$$

→  $\tilde{t}_1$  is optimal in the worst case (pessimistic)!

## $\Gamma$ -minimax, $\Gamma$ -minimin and a mixture

### $\Gamma$ -minimax ( $\Gamma$ -maximin)

- ▶ Find a decision  $\tilde{t}_1$  which minimizes the upper bound

$$\bar{\pi}[W.(t)] = \text{upper Bayes risk}$$

→  $\tilde{t}_1$  is optimal in the worst case (pessimistic)!

**Popular in robust Bayesian statistics.**

## $\Gamma$ -minimax, $\Gamma$ -minimin and a mixture

### $\Gamma$ -minimax ( $\Gamma$ -maximin)

- ▶ Find a decision  $\tilde{t}_1$  which minimizes the upper bound

$$\bar{\pi}[W.(t)] = \text{upper Bayes risk}$$

→  $\tilde{t}_1$  is optimal in the worst case (pessimistic)!

## $\Gamma$ -minimax, $\Gamma$ -minimin and a mixture

### $\Gamma$ -minimax ( $\Gamma$ -maximin)

- ▶ Find a decision  $\tilde{t}_1$  which minimizes the upper bound

$$\bar{\pi}[W.(t)] = \text{upper Bayes risk}$$

→  $\tilde{t}_1$  is optimal in the worst case (pessimistic)!

### $\Gamma$ -minimin ( $\Gamma$ -maximax)

- ▶ Find a decision  $\tilde{t}_2$  which minimizes the lower bound

$$\underline{\pi}[W.(t)] = \text{lower Bayes risk}$$

→  $\tilde{t}_2$  is optimal in the best case (optimistic)!

## $\Gamma$ -minimax, $\Gamma$ -minimin and a mixture

### $\Gamma$ -minimax ( $\Gamma$ -maximin)

- ▶ Find a decision  $\tilde{t}_1$  which minimizes the upper bound

$$\bar{\pi}[W.(t)] = \text{upper Bayes risk}$$

→  $\tilde{t}_1$  is optimal in the worst case (pessimistic)!

### $\Gamma$ -minimin ( $\Gamma$ -maximax)

- ▶ Find a decision  $\tilde{t}_2$  which minimizes the lower bound

$$\underline{\pi}[W.(t)] = \text{lower Bayes risk}$$

→  $\tilde{t}_2$  is optimal in the best case (optimistic)!

### and a mixture

- ▶ Find a decision  $\tilde{t}_3$  which minimizes a convex combination of the lower and the upper bound

$$\alpha \bar{\pi}[W.(t)] + (1 - \alpha) \underline{\pi}[W.(t)]$$

→ compromise between pessimism and optimism

## E-admissibility and Maximality

Let

$$\mathcal{P} = \{ \pi \text{ precise prior} \mid \underline{\pi}[h] \leq \pi[h] \leq \bar{\pi}[h] \quad \forall h \in \mathcal{L}_\infty(\Theta) \}$$

be the credal set of the imprecise prevision.

### E-admissibility

- Find a decision  $\tilde{t}_4$  which minimizes

$$\pi[W.(t)] = \int_{\Theta} W_{\theta}(t) \pi(d\theta)$$

for at least one  $\pi \in \mathcal{P}$ .

## E-admissibility and Maximality

Let

$$\mathcal{P} = \{ \pi \text{ precise prior} \mid \underline{\pi}[h] \leq \pi[h] \leq \bar{\pi}[h] \quad \forall h \in \mathcal{L}_\infty(\Theta) \}$$

be the credal set of the imprecise prevision.

### E-admissibility

- Find a decision  $\tilde{t}_4$  which minimizes

$$\pi[W.(t)] = \int_{\Theta} W_{\theta}(t) \pi(d\theta)$$

for at least one  $\pi \in \mathcal{P}$ .

### Minimality (Maximality)

- Find a decision  $\tilde{t}_5$  such that: For every  $t \in \mathbb{D}$ , there is at least one  $\pi_t \in \mathcal{P}$  such that

$$\pi_t[W.(\tilde{t}_5)] \leq \pi_t[W.(t)]$$

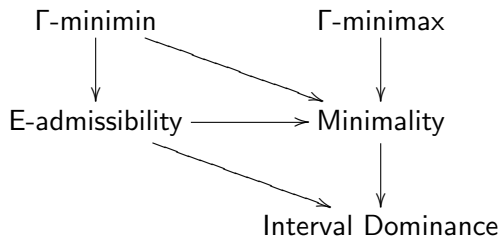
## Interval dominance

- ▶ A decision  $\tilde{t}_6$  is optimal with respect to **interval dominance** if there is no decision  $t \in \mathbb{D}$  such that

$$\bar{\pi}[W.(t)] \leq \underline{\pi}[W.(\tilde{t}_6)]$$

## Which is the right one?

The following implications hold:



Confer Troffaes (2007).

## How to calculate an optimal decision?

- ▶ In case of a finite  $\Theta = \{\theta_1, \dots, \theta_m\}$ :
  - ▶ Calculations by linear programming
  - ▶ See Utkin & Augustin (2005) and Kikuti et al. (2005).
- ▶ In case of an infinite  $\Theta$ :
  - ▶  $\Theta$  can be discretized
  - ▶ Decision problems can be approximately solved by linear programming
  - ▶ See Troffaes (2008).

## Data-Based Decision Theory

Often: Decision making on base of observations is possible

Observation / data  $x$        $\longrightarrow$       decision  $t = \delta(x)$

Example: Statistical decision theory is always data-based

## Data-Based Decision Theory

Often: Decision making on base of observations is possible

Observation / data  $x$   $\longrightarrow$  decision  $t = \delta(x)$

Example: Statistical decision theory is always data-based

So, we have

- ▶ a **sample space**  $(\mathcal{X}, \mathcal{A})$
- ▶ an **observation**  $x \in \mathcal{X}$
- ▶ a **distribution of the observation**

$x \sim P_\theta$  (depending on the state of nature  $\theta$ )

We have to **choose** not only one decision  $t$  but a **decision function**

$\delta: \mathcal{X} \rightarrow \mathbb{D}, \quad x \mapsto \delta(x)$

## Data-Based Decision Theory

**The Bayes risk of a decision function**  $\delta : x \mapsto \delta(x)$

- ▶ **Precise** previsions:

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta)$$

## Data-Based Decision Theory

**The Bayes risk of a decision function**  $\delta : x \mapsto \delta(x)$

- ▶ **Precise** previsions:

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta)$$

- ▶ **Imprecise** previsions:

$$\left\{ \int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- ▶  $\mathcal{P}$  credal set of an imprecise prevision of  $\theta$
- ▶  $\mathcal{M}_{\theta}$  credal set of an imprecise prevision of the observation  $x$   
 $\rightarrow$  imprecise model  $(\mathcal{X}, \mathcal{A}, (\mathcal{M}_{\theta})_{\theta \in \Theta})$

## Example: Estimating (Statistical Decision Theory)

Data  $x_1, \dots, x_n$  are modeled by a vector of random variables

$$X = (X_1, \dots, X_n) \sim P_0$$

$P_0$  is the true (precise) distribution.

## Example: Estimating (Statistical Decision Theory)

Data  $x_1, \dots, x_n$  are modeled by a vector of random variables

$$X = (X_1, \dots, X_n) \sim P_0$$

$P_0$  is the true (precise) distribution.

**Assumptions: precise case**

- ▶  $\{P_\theta \mid \theta \in \Theta\}$  a known parametric set of **precise** distributions
- ▶ There is a true parameter  $\theta_0 \in \Theta$  such that  $P_0 = P_{\theta_0}$
- ▶ There might be a **precise prior**  $\pi$  on  $\Theta$ .

## Example: Estimating (Statistical Decision Theory)

Data  $x_1, \dots, x_n$  are modeled by a vector of random variables

$$X = (X_1, \dots, X_n) \sim P_0$$

$P_0$  is the true (precise) distribution.

**Assumptions: precise case**

- ▶  $\{P_\theta \mid \theta \in \Theta\}$  a known parametric set of **precise** distributions
- ▶ There is a true parameter  $\theta_0 \in \Theta$  such that  $P_0 = P_{\theta_0}$
- ▶ There might be a **precise prior**  $\pi$  on  $\Theta$ .

**Decision theoretic formalization:**

- ▶ States of nature: the possible parameters  $\theta \in \Theta$
- ▶ Decision function: an estimator  $S$

$$\delta = S : \mathcal{X} \rightarrow \mathbb{D} = \Theta, \quad x \mapsto S(x)$$

- ▶ Loss function: e.g. the least squares loss

$$W_\theta(S(x)) = (\theta - S(x))^2 \quad \forall \theta \in \Theta$$

## Example: Estimating (Statistical Decision Theory)

Data  $x_1, \dots, x_n$  are modeled by a vector of random variables

$$X = (X_1, \dots, X_n) \sim P_0$$

$P_0$  is the true (precise) distribution.

**Assumptions: imprecise case**

- ▶  $\{\mathcal{M}_\theta \mid \theta \in \Theta\}$  a known parametric set of **imprecise** distributions
- ▶ There is a true parameter  $\theta_0 \in \Theta$  such that  $P_0 \in \mathcal{M}_{\theta_0}$
- ▶ There is a **imprecise prior**  $\mathcal{P}$  on  $\Theta$ .

**Decision theoretic formalization:**

- ▶ States of nature: the possible parameters  $\theta \in \Theta$
- ▶ Decision function: an estimator  $S$

$$\delta = S : \mathcal{X} \rightarrow \mathbb{D} = \Theta, \quad x \mapsto S(x)$$

- ▶ Loss function: e.g. the least squares loss

$$W_\theta(S(x)) = (\theta - S(x))^2 \quad \forall \theta \in \Theta$$

## Example: Estimating (Statistical Decision Theory)

The Bayes risk of an estimator  $S : x \mapsto S(x)$

- ▶ **Precise** previsions:

$$\int_{\Theta} \int_{\mathcal{X}} (\theta - S(x))^2 P_{\theta}(dx) \pi(d\theta)$$

- ▶ **Imprecise** previsions:

$$\left\{ \int_{\Theta} \int_{\mathcal{X}} (\theta - S(x))^2 P_{\theta}(dx) \pi(d\theta) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- ▶  $\mathcal{P}$  credal set of an imprecise prevision of  $\theta$
- ▶  $\mathcal{M}_{\theta}$  credal set of an imprecise prevision of the observation  $x$   
 $\rightarrow$  imprecise model  $(\mathcal{X}, \mathcal{A}, (\mathcal{M}_{\theta})_{\theta \in \Theta})$

## How to solve data-based decision problems?

In case of **precise** previsions:

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta)$$

- ▶ **By updating:** Find a decision  $\delta(x) \in \mathbb{D}$  which minimizes

$$\int_{\Theta} W_{\theta}(\delta(x)) \pi(d\theta|x) = \text{posterior Bayes risk}$$

- ▶ **Without updating:** Find a decision function  $\delta : \mathcal{X} \rightarrow \mathbb{D}$  which minimizes

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) = \text{Bayes risk}$$

## How to solve data-based decision problems?

In case of **precise** previsions:

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta)$$

- ▶ **By updating:** Find a decision  $\delta(x) \in \mathbb{D}$  which minimizes

$$\int_{\Theta} W_{\theta}(\delta(x)) \pi(d\theta|x) = \text{posterior Bayes risk}$$

- ▶ **Without updating:** Find a decision function  $\delta : \mathcal{X} \rightarrow \mathbb{D}$  which minimizes

$$\int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) = \text{Bayes risk}$$

**Both ways are equivalent!**

## How to solve data-based decision problems?

In case of **imprecise** previsions:

$$\left\{ \int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- Again, we have a whole set of (possible) Bayes risks.
- Again, different optimality criteria can be used.

## How to solve data-based decision problems?

In case of **imprecise** previsions:

$$\left\{ \int_{\Theta} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- Again, we have a whole set of (possible) Bayes risks.
- Again, different optimality criteria can be used.

The  $\Gamma$ -**minimax** criterion is used in the following.

## How to solve data-based decision problems?

In case of **imprecise** previsions:

- ▶ **By updating:** Find a decision  $\delta(x) \in \mathbb{D}$  which minimizes

$$\sup_{\pi \in \mathcal{P}_x} \int_{\Theta} W_{\theta}(\delta(x)) \pi(d\theta|x) = \text{upper posterior Bayes risk}$$

$$\text{where } \mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- ▶ **Without updating:** Find a decision function  $\delta : \mathcal{X} \rightarrow \mathbb{D}$  which minimizes

$$\sup_{\pi \in \mathcal{P}} \int_{\Theta} \sup_{P_{\theta} \in \mathcal{M}_{\theta}} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) = \text{upper Bayes risk}$$

## How to solve data-based decision problems?

In case of **imprecise** previsions:

- ▶ **By updating:** Find a decision  $\delta(x) \in \mathbb{D}$  which minimizes

$$\sup_{\pi \in \mathcal{P}_x} \int_{\Theta} W_{\theta}(\delta(x)) \pi(d\theta|x) = \text{upper posterior Bayes risk}$$

$$\text{where } \mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_{\theta} \in \mathcal{M}_{\theta} \forall \theta \in \Theta \right\}$$

- ▶ **Without updating:** Find a decision function  $\delta : \mathcal{X} \rightarrow \mathbb{D}$  which minimizes

$$\sup_{\pi \in \mathcal{P}} \int_{\Theta} \sup_{P_{\theta} \in \mathcal{M}_{\theta}} \int_{\mathcal{X}} W_{\theta}(\delta(x)) P_{\theta}(dx) \pi(d\theta) = \text{upper Bayes risk}$$

**Both ways are not equivalent!** (See e.g. Augustin (2003).)

# Calculations in data-based decision problems?

In case of **imprecise** previsions:

► **Solution by updating:**

- In general, it is hard to compute the set of all (possible) posteriors

$$\mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_\theta \in \mathcal{M}_\theta \forall \theta \in \Theta \right\}$$

- Once  $\mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_\theta \in \mathcal{M}_\theta \forall \theta \in \Theta \right\}$  is calculated, problem can be treated as a data-free problem.

# Calculations in data-based decision problems?

In case of **imprecise** previsions:

▶ **Solution by updating:**

- ▶ In general, it is hard to compute the set of all (possible) posteriors

$$\mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_\theta \in \mathcal{M}_\theta \forall \theta \in \Theta \right\}$$

- ▶ Once  $\mathcal{P}_x = \left\{ \pi(\cdot|x) \mid \pi \in \mathcal{P}, P_\theta \in \mathcal{M}_\theta \forall \theta \in \Theta \right\}$  is calculated, problem can be treated as a data-free problem.

▶ **Solution without updating:**

- ▶ If  $\Theta$  and  $\mathcal{X}$  are finite, calculations by linear programming
- ▶ Computationally costly and, quite often, intractable so far

## Other/Further Generalizations of Decision Theory

- ▶ **Imprecise loss functions**
- ▶ **Fuzzy sets**
- ▶ **Dempster-Shafer theory**
- ▶ ...

## Some References

- ▶ J.O. Berger. *Statistical decision theory and Bayesian analysis*. Springer-Verlag, New York, second edition, 1985.
- ▶ H. Strasser. *Mathematical theory of statistics. Statistical experiments and asymptotic decision theory*. Walter de Gruyter & Co. Berlin, 1985.
- ▶ M.C.M. Troffaes. Decision making under uncertainty using imprecise probabilities. *International Journal of Approximate Reasoning*, 45:17-29, 2007.
- ▶ T. Augustin. On the suboptimality of the generalized Bayes rule and robust Bayesian procedures from the decision theoretic point of view: a cautionary note on updating imprecise priors. In J.M. Bernard, T. Seidenfeld, and M. Zaffalon, editors, *Proceedings of ISIPTA'03*, pages 31-45. Carleton Scientific, Waterloo, 2003.
- ▶ R. Hable. *Data-based decisions under complex uncertainty*. Ph.D. Thesis, LMU Munich, 2009.  
<http://edoc.ub.uni-muenchen.de/9874/>